Calibration Techniques for Ultrasonic Tension Measurement

by Dave Archer

INTRODUCTION

The fundamentals of using ultrasonic pulse-echo technology for bolt strain measurement, detecting change in the time required for a pulse of energy to travel the length of the fastener after elongation, can be performed with very good resolution and repeatability. The challenge is utilizing this core capability in a manner such that the resulting calculation of bolt tension is also accurate and repeatable. Traditionally, the primary barriers to this have been in three areas: maintaining a stable bolt-sensor interface where the pulse passes into and out of the fastener, accounting for the influence of temperature on the measurement, and providing an accurate means of converting a given change in the pulse's time-of-flight (TOF) to usable units of tension or load. The last is generally referred to as calibration.

Recent developments that affix the sensor to the fastener, leaving the bolt-sensor interface a fixed and permanent condition, have largely solved the interface instability problems associated with separate sensors and liquid coupling. Temperature management and compensation remains a challenge to varying degree for both ultrasonics and other measurement techniques. As issues and solutions to temperature management are very application-dependent they won't be covered in this article. In general the desire is

simply to minimize temperature differentials and gradients. Conversely, the means of effectively converting TOF to tension can be discussed in manner that is widely applicable and will thus be the subject of this article. An attempt will be made to address both experienced and novice practitioners.

OBJECTIVE

We will compare the effectiveness of common calibration methods for use in both the elastic and plastic range of elongation. These methods are summarized in Table 1.

Table 1 - Calibration Methods Compared

	Regression Fit	Elongation Method
1	Linear	Torque
2	Non-Linear (5th order)	Torque
3	Linear	Tension
4	Non-Linear (5th order)	Tension

In all these four methods as a fastener under calibration is increasingly loaded, both the TOF of the ultrasonic pulse and the load required to produce the elongation (and increase the TOF) are monitored. A series of load/TOF data pairs are produced for each sample, and once all samples have been calibrated regression analysis is run to predict the bolt tension for a given TOF.

Figure 1 illustrates the relationship between bolt elongation and the resulting bolt tension. Line A-B-C represents the behavior of a bolt loaded into yield, with permanent elongation occurring after point B. While this trace is often produced by pulling the bolt in a tensile tester, compressing a load cell by rotating the bolt into a nut member

produces the same effect. Finally, since the change in TOF is directly proportional to elongation, line A-B-C also represents the response of an ultrasonic sensor as measured by TOF. As most bolted joints are designed for bolt load to remain within the elastic range (Line A-B), it is common to calibrate within this range only and produce a simple linear estimate for Load vs. ΔTOF . These linear calibrations can also be used to measure tension in bolts that have been permanently elongated by taking the installed tension measurement, fully loosening the bolt and measuring the residual "tension" due to permanent elongation and then subtracting this residual value from the initial reading. Because a linear relationship between TOF and load treats all changes in TOF the same, a given increase in elongation produces the same estimate of increased load in all situations. Therefore, when the actual relationship between elongation and load follows Line B-C, the ultrasonic system with linear calibration will incorrectly predict load along Line B-C2. However, the final TOF will be the same in both cases. When loosened, the bolt's elastic elongation is relieved by following the same path as during the elastic phase of tightening: Line C-D (parallel to Line A-B). The residual "tension" displayed on the ultrasonic measuring system will be Point D2, based on the TOF at Point D. This differential load, represented by Line D-D2, is equal to the differential load represented by Line C-C2 as the lines are of equal length. Subtracting load D2 from the value at Point C2 yields the correct value: Point C.

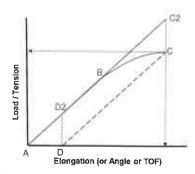


Figure 1 - Load vs. elongation into yield with notation on correcting linear calibrations for plastic deformation.

Some users with the capability for non-linear calibration use it for all applications whether or not the bolt is to be permanently elongated although the capability for non-linear calibration is not available in all measurement systems. So the calibration method that will be used for given application is not always a given, particularly considering the fact that both tensile and torque-based loading methods are possible. This is the motivation for comparing the effectiveness of the four options summarized in Table 1.

TEST PROCEDURE

The approach taken was to generate calibration files using the four combinations of regression fit and elongation, then tighten a series of bolts in a load cell and compare the ultrasonic tension calculated using each of the four calibrations to the output from the load cell. The load cell would be considered the control, and deviation from the load cell would be considered measurement error.

The equipment used in the test is summarized in Table 2. Class 8.8 bolts were chosen for convenience. but all the trends shown here are applicable to other property classes. As noted, the setup used to conduct the comparison test is the same one used for the torque calibration. To enable the most direct comparison of linear and non-linear calibration. the linear calibration was not created with an independent set of samples, but rather the series of data pairs generated over the full range of elongation into yield was cropped so that just the points recorded in the elastic range remained.

Table 2 - Test Equipment

Bolt	M10x1.5x70 class 8.8 hex flange head zinc electroplated (grip 55.2 mm)
Nut	M10x1.5 class 8 zinc electroplated (Alt Nut Factor test: class 10 plain)
Washer	Hardened zinc electroplated (square test washer)
Test Cell - Tensile Cal	Twin ball screw Universal Test Machine
Test Cell - Torque Cal	Torque-Tension Test Cell - Strain gage-based external torque-angle transducer and load cell
Test Cell - Cal Comparison	Same as Test Cell - Torque Cal
Ultrasonic System	Dedicated hardware and software with bonded sensors and removable magnetic pickup (no temperature compensation)

TEST RESULTS

The results of comparing load cell tension to tension calculated from the four forms of ultrasonic calibrations are summarized in Table 3a thru 3d. Each table covers a different measurement scenario. Table 3a is a compilation of intermediate measurements, all within the elastic range, taken at the most common design targets for bolt tension. The three subsequent tables are the final tension readings for bolts elongated into yield. The difference between Table 3b and 3c is how far into the plastic range the bolt was elongated. Table 3d is unique in that for all other cases the bolt, nut and washer used for the comparative test were the same used for calibration. The results shown in Table 3d reflect use of a plain finish nut rather than the zinc-plated nut used in all other cases. In all tables variation is defined as the absolute value of the difference in ultrasonic tension relative to load cell tension.

Table 3a - Tension in Elastic Range Intermediate Value (70%, 80%, 90% Proof Load)				
	5th Order Torque	5th Order Tension	Linear Torque	Linear Tension
Mean Deviation	2.4%	2.4%	0.6%	0.7%
Max Deviation	3.7%	3.7%	1.8%	1,4%
Min Deviation	1.2%	0.9%	0.0%	0.0%

36 Data Points/Cell

Table 3b - Tension in Plastic Range Final Value (40kN + 45°)				
	5th Order Torque	5th Order Tension	Linear Torque	Linear Tension
Mean Deviation	0.9%	4.7%	1.0%	1.0%
Max Deviation	1.6%	6.4%	3.0%	2.9%
Min Deviation	0.4%	3.5%	0.0%	0.2%

12 Data Points/Cell

	5th Order Torque	5th Order Tension	Linear Torque	Linear Tension
Mean Deviation	1.1%	6.1%	3.9%	3.8%
Max Deviation	1,5%	7.9%	6.0%	5.9%
Min Deviation	0.7%	5.3%	1.1%	1,2%

6 Data Points/Cell

	5th Order Torque	5th Order Tension	Linear Torque	Linear Tension
Mean Deviation	6.1%	10.8%	1.2%	1.4%
Max Deviation	9,5%	14.0%	1.5%	1.7%
Min Deviation	2.9%	7,6%	0.9%	1.1%

6 Data Points/Cell

COMMENTS ON TEST RESULTS

· The difference in tension calculated by linear torque and tension calibrations were approximately 0.1%. This reinforces our past experience that in the elastic range either elongation method can be equally accurate. It may seem odd that the non-linear calibrations resulted in about three times the deviation when the linear calibrations were derived directly from them. The reason is shown in Figure 2. Even when using 5th order regression, the portion of the calibration covering the proportional elastic range deviates from linear. While the tensile method of calibration allows use of cal bolts for testing as the contact surfaces are unaltered, one tends to need more care in establishing grip length in tensile calibration due to the nature of the tooling. This is particularly true as grip length decreases. To approximate the small increase in stiffness of advancing the bolt during torque calibration we set the grip length for tensile calibration sort of the

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calculated value by 10% of the thread pitch (half the rotation assuming it was 72° from threshold). Where possible, it is desirable to simulate actual thread engagement as this influences bolt stiffness, and therefore calibration.

• The three tests conducted in the plastic range highlight the advantages and disadvantages of each calibration. First, the tension-based nonlinear results show greater deviation than those, which are torque-based. The reason for this is also the reason that the non-linear calibrations perform poorly in Table 3d. In both cases the limit of the proportional elongation is reduced by the addition of torsional stress. This is illustrated in Figure 3 highlighting the area around yield of three tension-angle traces recorded on the torque

test cell. The three traces are the calibration and primary test hardware (nut factor K=0.164), the plain nut used only in the Table 3d test (K=0.184), and a third set tested for this illustration only (K=0.273). If the trace from a pure tensile pull were added, the proportional limit would be still higher than that for the primary test hardware. Fortunately, because actual fastener proof loads are often 15% to 20% higher than minimum requirements, finishes with reasonably low nut factors result in proportion limits above minimum proof. The increasingly indistinct deviation from proportionality that occurs with increasing tensional stress should be kept in mind when analyzing torque-angle or tension-angle traces, as it can be mistaken for the onset of embedment.

- Another finding of the measurements into yield is that the
 process of using linear calibrations and subtracting the
 permanent elongation from the as-tightened tension results in
 accurate measurement, particularly when plastic elongation is
 short. We have found that best results are obtained recording
 the residual value immediately after loosening. The fastener
 continues to contract a small amount for a period thereafter in
 what appears to be a recovery mechanism rather than being
 temperature-related.
- It is important to point out that using non-linear calibration for measurement in the plastic range other than for the initial tension after tightening can be very inaccurate. For example, any tension relaxation after tightening into yield would follow Line C-D in Figure 1. However, the relaxation predicted by the non-linear calibration would be underestimated, following the same Line B-C used for estimated increasing tension. If service loads were to further increase permanent elongation it is not assured that Line B-C would be followed. Because the torsional stress is removed, recovery from relaxation could instead follow a parallel path resulting from extending the higher proportional limit due to pure tensile stress. Within limits, subtracting the residual elongation from the linear calibration measurement can still be used in these situations.



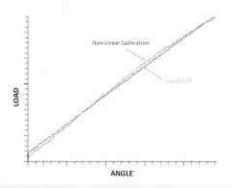


Figure 2 - Comparison of ultrasonic load calculation using 5th order calibration relative to "control" load cell measurement within the elastic range of elongation

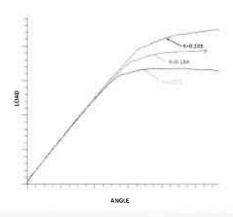


Figure 3 - The effect of torsional stress on the proportional limit of elongation

SUMMARY

Like any single test that is intended to predict a much wider set of conditions, the key question for these results is how widely and reliably can they be applied. Our experience is that the trends and relative accuracy is representative of most applications. The absolute accuracy is less certain. As noted, because the control test setup was the same used to calibrate the torque calibration, variation was essentially a test of calibration repeatability. The 1% accuracy achieved here is achievable over a range of typical applications, but can be compromised by short grip lengths, fastener materials and certain geometries. An estimate of a lower accuracy limit might be 5% with some exceptions. Both non-linearity and slope variation tend to be effected. Poor repeatability with good linearity tends to

point to tooling issues that can usually be rectified. As another point of comparison, we performed a similar test in the elastic range using linear tensile calibration to determine measurement uncertainty for ISO:17025 certification. The result was an expanded uncertainty of 0.816% with a coverage factor of 2.

Even for applications at lower limits of calibration accuracy, because it is only commercially-available means by which bolt tension may be measured without functional change to the fastener or the joint members, ultrasonic measurement is still highly effective relative to alternative techniques. Finally, while hardware and software advancements have reduced operator impact and the need for interpretation that were typical of early ultrasonic use, the measuring system and the person using it are still influential.

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